Discretising the Navier-Stokes-Onsager-Stefan-Maxwell equations of multicomponent flow

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This talk

We describe a class-I model, the Navier-Stokes-Onsager-Stefan-Maxwell equations.

Section 2

Examples

We consider the microfluidic mixing of benzene (C_6H_6) and cyclohexane (C_6H_{12}) .



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We use order five finite elements in a curved geometry: discrete problem has 6m unknowns. 5/42



Mole fraction x_1 of benzene and streamlines of its velocity v_1 .

A Hull cell is a device used to test electroplating.





A Hull cell.

The electroplating of copper.

Images from www.yamamoto-ms.co.jp/en/what-is-hull-cell/ and en.wikipedia.org/wiki/Electroplating.

We consider LiPF₆ in ethyl methyl carbonate (EMC), which dissolves into Li⁺ and PF₆⁻.



We model the electroplating of lithium from the anode to the cathode. We impose a voltage difference of 10 mV, and Robin conditions on the current and lithium flux.

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We fit ionic conductivity, Stefan–Maxwell diffusivity, Darken factor, cation transference number, and density from experimental data reported by

A. A. Wang et al. "Shifting-reference concentration cells to refine composition-dependent transport characterization of binary lithium-ion electrolytes". In: *Electrochimica Acta* 358 (2020), p. 136688. DOI: 10.1016/j.electacta.2020.136688.



Solvent streamlines and mole fraction.

Section 3

The model

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We present the model in isothermal, nonreactive conditions.

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... but our numerics haven't gotten that far yet.



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Wolfgang Dreyer 11 / 42

Subsection 1

Continuity equations

Mass continuity in the absence of chemical reactions requires that

$$\partial_t \rho_i + \nabla \cdot (\rho_i v_i) = 0,$$

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The relation

$$\rho v = \sum_{i} \rho_i v_i$$

is the mass-average constraint on the fluxes.

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This is reasonable when

$$\frac{UV}{C^2} \ll 1$$

where U is the reference diffusive speed, V is the reference speed, and $C = \sqrt{p_0/\rho_0}$ is on the order of the speed of sound. Here p_0 is the reference pressure and ρ_0 the reference density.

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Onsager relations

We employ Onsager's linear framework for constitutive relations (more later).

Subsection 2

Momentum equation

The balance equation we solve for v is the usual Cauchy momentum equation with pressure p, deviatoric stress S and body force f:

$$\partial_t(\rho v) + \nabla \cdot (\rho v \otimes v) + \nabla p - \nabla \cdot \mathbb{S} = \rho f.$$



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We again require a constitutive equation relating $\mathbb{D}v$ to \mathbb{S} . We employ the usual Newtonian relation:

$$\mathbb{S} = 2\mu \mathbb{D}v + \lambda (\nabla \cdot v)\mathbb{I}.$$



Augustin-Louis Cauchy
Subsection 3

Constitutive relations for transport

The entropy production ξ in the isothermal, nonreactive case is given by

$$T\xi = \sum_{i} d_i \cdot (v_i - v) + \mathbb{S} : \mathbb{D}v$$

where d_i are the diffusion driving forces

$$d_i \coloneqq -c_i \nabla \mu_i + (\rho_i / \rho) \nabla p,$$



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with μ_i the *(electro)chemical potential* of species i, $c_i := \rho_i/M_i$ its molar concentration, and M_i is its molar mass.

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Employing the constitutive framework of Onsager yields

$$d_i = \sum_{j=1}^N \mathcal{M}_{ij}(v_j - v), \quad \mathbb{D}v = \mathcal{A}\mathbb{S},$$

where \mathcal{M} and \mathcal{A} are symmetric positive semi-definite operators (at least).

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The Onsager transport matrix M_{ij} models the drag exerted between species, and encodes Stefan–Maxwell coefficients:

$$\mathcal{M}_{ij} := \begin{cases} -\frac{RTc_ic_j}{\mathscr{D}_{ij}c_T} & \text{if } i \neq j, \\ \sum_{k=1, k \neq i}^n \frac{RTc_ic_k}{\mathscr{D}_{ik}c_T} & \text{if } i = j, \end{cases}$$

where $c_T \coloneqq \sum_i c_i$. \mathcal{M} thus depends nonlinearly on our state variables. The Stefan–Maxwell diffusivities \mathcal{D}_{ij} can also depend on concentrations and pressure.

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More significantly, the matrix \mathcal{M}_{ij} is singular with nullspace of constants (if all species are present in nonzero amounts). The Onsager–Stefan–Maxwell equations

$$d_i = \sum_{j=1}^N \mathcal{M}_{ij}(v_j - v)$$

therefore appear ill-posed?

The remedy is to realise that the diffusion driving forces must satisfy the ${\it Gibbs-Duhem}$ relation

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Imposing the mass-average constraint

$$\rho v = \sum_{i} \rho_i v_i$$

finally yields a unique solution for $\{v_i\}$.



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Subsection 4

Constitutive relations for thermodynamics

Let's gather the equations we have seen so far.

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$$\begin{split} \partial_t \rho_i + \nabla \cdot (\rho_i v_i) &= 0 & \forall i \in 1:N, \\ \partial_t (\rho v) + \nabla \cdot (\rho v \otimes v) + \nabla p - \nabla \cdot (\mathcal{A}^{-1} \mathbb{D} v) &= \rho f, \\ \rho &= \sum_j \rho_j, \\ \rho v &= \sum_j \rho_j v_j, \\ d_i (T, p, \{\rho_j\}, \{\mu_j\}) &= \sum_j \mathcal{M}_{ij} (T, p, \{\rho_l\}) (v_j - v) & \forall i \in 1:N. \end{split}$$

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This still is not closed: the diffusion driving forces depend on chemical potentials $\{\mu_i\}$, but do not yet have equations for them.

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What happens when the partition is removed?

The two gases exchange volume until the pressures equalise. Why?



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For any thermodynamic potential, these variables can be paired, with units of energy:

 $\mathrm{d}G = -T\mathrm{d}S + V\mathrm{d}P + \sum_{i} \mu_{i}\mathrm{d}n_{i},$

where G is the Gibbs free energy.



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Particles tend to move from higher to lower chemical potentials because this reduces the free energy.

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If we determine $\{x_i\}$ and c_T , we can compute the partial densities via

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With this, we close the system with given thermodynamic relations of the form

$$\mu_i = g_i(T, p, \{x_j\})$$

1/c_T = $\sum_i x_i V_i(T, p, \{x_j\})$

where $\{g_i\}$ are partial molar Gibbs functions and $\{V_i\}$ are partial molar volume functions.

It might be useful to see concrete examples of these. For the benzene and cyclohexane mixture, we employ a Margules model

$$\mu_1 = g_1(T, p, x_1, x_2) = p/c_1^{\text{ref}} + RT \ln x_1 + RT x_2^2 (A_{12} + 2(A_{21} - A_{12})x_1),$$

$$\mu_2 = g_2(T, p, x_1, x_2) = p/c_2^{\text{ref}} + RT \ln x_2 + RT x_1^2 (A_{21} + 2(A_{12} - A_{21})x_2).$$

The reference values and coefficients are drawn from *Perry's Chemical Engineers' Handbook*:

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The partial molar volumes are then computed from

$$V_i \coloneqq \left(\frac{\partial \mu_i}{\partial p}\right)_{T,\{x_j\}}.$$



Max Margules





Subsection 5

Problem statement

We are now in a position to state the PDE system to solve:

$$\begin{split} \partial_t \rho_i + \nabla \cdot (\rho_i v_i) &= 0 & \forall i \in 1:N, \\ \partial_t (\rho v) + \nabla \cdot (\rho v \otimes v) + \nabla p - \nabla \cdot (\mathcal{A}^{-1} \mathbb{D} v) &= \rho f, \\ \rho &= \sum_j \rho_j, \\ \rho v &= \sum_j \rho_j v_j, \\ d_i (T, p, \{\rho_j\}, \{\mu_j\}) &= \sum_j \mathcal{M}_{ij} (T, p, \{\rho_l\}) (v_j - v) & \forall i \in 1:N, \\ \rho_i &= x_i M_i c_T & \forall i \in 1:N, \\ \sum_j x_j &= 1, \\ \mu_i &= g_i (T, p, \{x_j\}) & \forall i \in 1:N, \\ c_T^{-1} &= \sum_j x_j V_j (T, p, \{x_j\}). \end{split}$$

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We also need initial and boundary conditions, of course!

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Section 4

Simplifications
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Each solute in a dilute mixture interacts almost solely with solvent molecules, so the solute fluxes can be modelled by Fick's law:

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Consequence

The system reduces to usual Navier–Stokes + decoupled convection-diffusion equations.

Ideal mixture

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An added benefit: Stefan-Maxwell diffusivities are much better approximated by constants.

Section 5

Discretisation

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Our current preferred variational formulation solves

Primary variables

$$\{x_i\} \in [L^2]^N,$$

$$\{\mu_i\} \in [L^2]^N,$$

$$v \in H^1 \otimes \mathbb{R}^d,$$

$$p \in L^2,$$

$$\rho^{-1} \in H^1,$$

$$\{J_i\} \in [H(\operatorname{div})]^N$$

where the species mass fluxes relate to the species velocities by

$$J_i = \rho_i v_i.$$

The other variables are eliminated algebraically.

1. For mass continuity $\partial_t \rho + \nabla \cdot (\rho v) = 0$ to hold, we must satisfy the mass-average constraint

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The interplay between these constraints, and to what extent they imply one another, is very subtle, especially upon discretisation.

One strategy is to neglect pressure diffusion, eliminate one of the species velocities (say v_N), and invert the Onsager transport matrix to get the *Onsager–Fick* formulation:

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However, this has several disadvantages:

- only works for simple expressions for μ_i ;
- it neglects pressure diffusion (and other effects);
- it breaks the symmetry among the species;
- the $(N-1) \times (N-1)$ matrix D loses all structural properties: not even symmetric.

One strategy is to neglect pressure diffusion, eliminate one of the species velocities (say v_N), and invert the Onsager transport matrix to get the Onsager–Fick formulation:

$$v_i = \sum_{j=1}^{N-1} D_{ij} \nabla c_j \quad \forall i \in 1 : N-1.$$

However, this has several disadvantages:

- only works for simple expressions for μ_i ;
- it neglects pressure diffusion (and other effects);
- it breaks the symmetry among the species;
- the $(N-1) \times (N-1)$ matrix D loses all structural properties: not even symmetric.

This approach is not going to be structure-preserving.

Define $\omega_i \coloneqq \rho_i / \rho$, the mass fraction of species *i*. For an augmentation parameter $\gamma > 0$, we replace the Onsager–Stefan–Maxwell equations by

$$d_i + \underline{\gamma \omega_i v} = \sum_j \mathcal{M}_{ij}(v_j - v) + \underline{\gamma \omega_i \omega_j (v_j - v)}$$



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Vincent Giovangigli 37 / 42

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It turns out to be advantageous to add a dual augmentation to the momentum balance:

$$\partial_t(\rho v) + \nabla \cdot (\rho v \otimes v) + \nabla p - \nabla \cdot \mathbb{S} + \underline{\gamma v} - \underline{\gamma \sum \omega_j v_j} = \rho f.$$



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These are for incompressible flow, but they arise here, because instead of

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We discretise $({J_i}, {\mu_i}, {x_i})$ using mixed-Poisson elements, e.g.

 $J_i \in BDM_k, \quad \mu_i \in DG_{k-1}, \quad x_i \in DG_{k-1}, \quad i \in 1: N.$

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With this we can prove convergence and quasi-optimality of the discretisation for a Picard linearisation.

Solving the Newton iteration threw up many unanticipated subtleties.

First, the pressure diffusion term ∇p in d_i appears to lead to suboptimal convergence by one power of h. It's not clear how to circumvent this.

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Second, we need to add 'density consistency terms'. For the true solution, we have

$$v \cdot \nu = \sum_i \rho^{-1} J_i \cdot \nu,$$

where ν is the outward normal on $\partial\Omega$, but discretely we only satisfy the mass-average constraint approximately

$$v_h \cdot \nu \approx \sum_i \rho_h^{-1} J_{h,i} \cdot \nu,$$

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and we need to account for this in the discretisation.

However, we have solved these problems and now appear to have robust solvers in place!

Section 6

Conclusions

Good news

We can now robustly discretise the Navier–Stokes–Onsager–Stefan–Maxwell equations.

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Good news

I still think there are many important applications to be tackled.

Our immediate next steps are to use the thermal, electroneutral equations to simulate puzzling experiments for $LiPF_6$ in EMC.

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A key numerical question is efficient solvers. We now have excellent preconditioners for the non-ideal, thermal Onsager–Stefan–Maxwell equations with specified mass-average velocity, and we are starting on the full equations.

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Future work

Numerical analysis, applications in electrochemistry and physiology, porous media, non-Newtonian mixtures, phase change, chemical reactions,